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DS92LV222A Two Channel Bus LVDS MUXed Repeate

National Semiconductor

DS92LV222A Two Channel Bus LVDS MUXed Repeater

General Description

The DS92LV222A is a repeater designed specifically for the bridging of multiple backplanes in a rack. The DS92LV222A utilizes low voltage differential signaling to deliver high speed while consuming minimal power with reduced EMI. The RSEL pin and DE pins allow maximum flexibility as to which receiver/driver are used. The DS92LV222A repeats signals between backplanes and accepts or drives signals onto the local bus. It also features a flow through pin out which allows easy PCB routing for short stubs between its pins and the connector.

The driver is selectable between $3.5 \text{ mA} (100\Omega \text{ load})$ and $8.5 \text{ mA} (27\Omega \text{ load})$ output loop currents depending upon the level applied to the ISEL pin. This allows for single termination (point-to-point) and also double termination (multipoint) applications while maintain similar differential levels.

The receiver threshold is ± 100 mV, while providing $\pm 1V$ common mode range.

- Features
- Bus LVDS Signaling (BLVDS)
- Designed for Double Termination Applications
- Low power CMOS design
- High Signaling Rate Capability (above 100 Mbps)
- Ultra Low Power Dissipation (13.2 mW quiescent)
- Balanced Output Impedance
- Lite Bus Loading 5 pF typical
- Selectable Drive Capability (3.5 mA or 8.5 mA)
- 3.3V operation
- ±1V Common Mode Range
- ±100 mV Receiver Sensitivity
- Available in 16 pin SOIC package.



Absolute Maximum Ratings (Notes 1, 2)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

| Supply Voltage (V _{CC}) | 6.0V |
|-----------------------------------|-----------------------------------|
| Enable Input Voltage (DE) | –0.3V to (V _{CC} + 0.3V) |
| Current Select Voltage | -0.3V to (V ₂₂ + 0.3V) |
| Receiver Select Voltage | |
| (RSEL) | –0.3V to (V _{CC} + 0.3V) |
| Bus Pin Voltage (DO/RI±) | -0.3V to +3.9V |
| Driver Short Circuit Current | Continuous |
| ESD (HBM 1.5 kΩ, 100 pF) | >2 kV |
| Maximum Package Power Dissip | pation at 25°C |
| SOIC | 970 mW |

| 8mW/°C |
|-----------------|
| –65°C to +150°C |
| |
| 260°C |
| |

Recommended Operating Conditions

| | Min | Max | Units | |
|-----------------------------------|-----|-----|-------|--|
| Supply Voltage (V _{CC}) | 3.0 | 3.6 | V | |
| Receiver Input Voltage | 0.0 | 2.9 | V | |
| Operating Free Air Temperature | -40 | +85 | °C | |

DC Electrical Characteristics

 T_{A} = -40°C to +85°C unless otherwise noted, V_{CC} = 3.3V \pm 0.3V (Notes 2, 3)

| Symbol | Parameter | Conditions | Pin | Min | Тур | Max | Units |
|------------------------|---------------------------------|---|-----------------|------|------|-----------------|-------|
| DIFFERE | NTIAL DRIVER CHARACTE | RISTICS | | | | | |
| V _{OD} | Output Differential Voltage | $R_{L} = 27\Omega$ Figure 1 lsel = 0V | DO+, DO– | 170 | 220 | 280 | mV |
| ΔV_{OD} | VOD Magnitude Change | | | | 2 | 10 | mV |
| Vos | Offset Voltage | | | 1.0 | 1.25 | 1.6 | V |
| $\Delta V_{\rm OS}$ | Offset Magnitude Change | | | | 10 | 20 | mV |
| V _{OD} | Output Differential Voltage | $R_{L} = 100\Omega$ Figure 1 lsel = 3.3V | - | 250 | 360 | 480 | mV |
| ΔV_{OD} | VOD Magnitude Change | | | | 2 | 10 | mV |
| Vos | Offset Voltage | | | 0.9 | 1.25 | 1.6 | V |
| $\Delta V_{\rm OS}$ | Offset Magnitude Change | | | | 10 | 20 | mV |
| I _{OZD} | TRI-STATE [®] Leakage | $V_{O} = V_{CC}$ or GND, DE = 0 | | | ±1 | ±10 | μA |
| I _{OXD} | Power-Off Leakage | $V_{O} = 2.9V \text{ or GND},$ $V_{CC} = 0V$ | | | ±1 | ±10 | μA |
| I _{OSD} | Output Short Circuit Current | $ISEL = V_{CC}$ $V_{O} = 0V$ | | | -11 | -13 | mA |
| DIFFERE | NTIAL RECEIVER CHARAC | TERISTICS | | | | | |
| V_{TH} | Input Threshold High | | RI+, RI– | | | +100 | mV |
| V _{TL} | Input Threshold Low | | | -100 | | | mV |
| I _{IN} | Input Current | V_{IN} = +2.9V, or 0V, V_{CC} = 3.6 V or 0 V | | -10 | ±1 | +10 | μΑ |
| DEVICE (| CHARACTERISTICS | • | | | • | | |
| V _{IH} | Minimum Input High Voltage | | DE0, DE1, | 2.0 | | V _{cc} | V |
| V _{IL} | Maximum Input Low Voltage | | RSEL, ISEL0, | GND | | 0.8 | V |
| I _{IH} | Input High Current | V _{IN} = V _{CC} or 2.4V | ISEL1 | | ±1 | ±10 | μA |
| I _{IL} | Input Low Current | V _{IN} = GND or 0.4V | 1 | | ±1 | ±10 | μA |
| V_{CL} | Input Diode Clamp Voltage | $I_{CLAMP} = -18 \text{ mA}$ | | -1.5 | -0.8 | | V |

| DC Electrical Characteristics (Continued) | | | | | | | | |
|---|------------------------------|--|-----------------|-----|-----|-----|-------|--|
| $T_{A} = -40$ | 0°C to +85°C unless otherwis | e noted, $V_{CC} = 3.3V \pm 0.3V$ (| Notes 2, 3) | | | | | |
| Symbol | Parameter | Conditions | Pin | Min | Тур | Max | Units | |
| DEVICE | DEVICE CHARACTERISTICS | | | | | | | |
| I _{CCD} | Power Supply Current | No Load; DE = RSEL = V _{cc} Isel = 0 V | V _{cc} | | 25 | 45 | mA | |
| | | $R_L = 27\Omega$; DE = RSEL = V _{CC} lsel = 0 V | | | 24 | 40 | mA | |
| I _{ccz} | | $DE = 0V; RSEL = V_{CC}$ | | | 4 | 8 | mA | |
| C _{input} | Capacitance at | | RO+/RO- | | 5 | | pF | |
| C _{output} | Capacitance at | | DO+/DO- | | 5 | | pF | |

Note 1: "Absolute Maximum Ratings" are these beyond which the safety of the device cannot be guaranteed. They are not meant to imply that the device should be operated at these limits. The table of "Electrical Characteristics" provides conditions for actual device operation.

Note 2: All currents into device pins are positive; all currents out of device pins are negative. All voltages are referenced to device ground unless otherwise specified. Note 3: All typicals are given for V_{CC} = +3.3V and T_A = +25°C, unless otherwise stated.

Note 4: ESD Rating: HBM (1.5 k Ω , 100 pF) > 2 kV EIAJ (0 Ω , 200 pF) > 200V

Note 5: CL includes probe and fixture capacitance.

Note 6: Generator waveforms for all tests unless otherwise specified: f = 1MHz, ZO = 50Ω , t_f = < 6.0 ns (0%-100%).

Note 7: The DS92LV222A is a current mode device and only functions datasheet specifications when a resistive load is applied to the drivers outputs.

Note 8: During receiver select transition(s), data must be held in a steady state 15 ns before and 15 ns after the RSEL pin changes state.

Note 9: Channel-to-channel skew is the measurement between outputs of D0 and D1.

AC Electrical Characteristics

 $T_A = -40^{\circ}C$ to +85°C, $V_{CC} = 3.3V \pm 0.3V$ (Note 6)

| Symbol | Symbol Parameter Conditions | | Min | Тур | Max | Units |
|------------------------|--|--|------|-----|-----|-------|
| t _{TLH} | Transition Time Low to High | $R_L = 27\Omega$ Figures 2, 3 | 0.15 | 0.4 | 2.0 | ns |
| t _{THL} | Transition Time High to Low | $C_L = 10 \text{ pF}$ Figures 2, 3 | 0.15 | 0.4 | 2.0 | ns |
| t _{PHZ} | Disable Time High to Z | $R_L = 27\Omega$ Figures 4, 5 | 2.0 | 6.0 | 9.0 | ns |
| t _{PLZ} | Disable Time Low to Z | $C_L = 10 \text{ pF}$ Figures 4, 5 | 2.0 | 6.0 | 9.0 | ns |
| t _{PZH} | Enable Time Z to High | | 2.0 | 6.0 | 9.0 | ns |
| t _{PZL} | Enable Time Z to Low | | 2.0 | 6.0 | 9.0 | ns |
| DIFFERENT | IAL RECEIVER TO DRIVER TIMING REC | QUIREMENTS | | | | |
| t _{PHL_RD} | Differential Prop. Delay High to Low | $R_L = 27\Omega$ Figures 2, 3 | 3.0 | 7.7 | 13 | ns |
| t _{PLH_RD} | Differential Prop. Delay Low to High | $C_L = 10 \text{ pF}$ Figures 2, 3 | 3.0 | 8.0 | 13 | ns |
| t _{sk_RD} | Pulse SKEW t PHL -tPLH | | 0 | 0.3 | 2.0 | ns |
| t _{PHL_RS0} | Prop. Delay High to Low | RSEL to Driver Outputs | 2.0 | 7.5 | 13 | ns |
| t _{PLH_RS1} | Prop. Delay Low to High | $R_{L} = 2732$ Figures 6, 7 $C_{L} = 10 \text{ pF} (\text{Note 8})$ | 2.0 | 8.0 | 13 | ns |
| t _{PHL_R0 Dx} | Channel-to-Channel Skew R $_{\rm 0}$ to D $_{\rm x}$ | $R_L = 27\Omega$ | | 0.3 | 0.8 | ns |
| t _{PLH_R0 Dx} | Channel-to-Channel Skew R $_{0}$ to D _x | $C_L = 10 \text{ pF}$ | | 0.3 | 0.8 | ns |
| t _{PHL_R1 Dx} | Channel-to-Channel Skew R $_1$ to D _x | (Note 9) | | 0.3 | 0.8 | ns |
| t _{PLH_R1 Dx} | Channel-to-Channel Skew R 1 to Dx | | | 0.3 | 0.8 | ns |
| · · · · | | | | | | |

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Function Select Table

| MODE SELECTEDDEReceiver Zero ON, Driver Zero ON, Driver One OFFHReceiver Zero ON, Driver Zero OFF, Driver One ONLReceiver One ON, Driver Zero ON, Driver One OFFHReceiver One ON, Driver Zero OFF, Driver One ONLReceiver Zero ON, Driver Zero OFF, Driver One ONHReceiver Zero ON, Driver Zero ON, Driver One ONHReceiver One ON, Driver Zero ON, Driver One ONHDriver Zero and Driver One TRI-STATEL | | | | | |
|--|---|--------------------------------|-----|-----|------|
| Receiver Zero ON, Driver Zero ON, Driver One OFF H Receiver Zero ON, Driver Zero OFF, Driver One ON L Receiver One ON, Driver Zero OFF, Driver One OFF H Receiver One ON, Driver Zero OFF, Driver One ON L Receiver Zero ON, Driver Zero OFF, Driver One ON L Receiver Zero ON, Driver Zero ON, Driver One ON H Receiver One ON, Driver Zero ON, Driver One ON H Receiver One ON, Driver Zero ON, Driver One ON H Driver Zero and Driver One TRI-STATE L | | MODE SELECTED | DE0 | DE1 | RSEL |
| Receiver Zero ON, Driver Zero OFF, Driver One ON L Receiver One ON, Driver Zero ON, Driver One OFF H Receiver One ON, Driver Zero OFF, Driver One ON L Receiver Zero ON, Driver Zero ON, Driver One ON H Receiver One ON, Driver Zero ON, Driver One ON H Receiver One ON, Driver Zero ON, Driver One ON H Driver Zero and Driver One TRI-STATE L | F | Driver Zero ON, Driver One OFF | Н | L | L |
| Receiver One ON, Driver Zero ON, Driver One OFF H Receiver One ON, Driver Zero OFF, Driver One ON L Receiver Zero ON, Driver Zero ON, Driver One ON H Receiver One ON, Driver Zero ON, Driver One ON H Driver Zero and Driver One TRI-STATE L | ١ | Driver Zero OFF, Driver One ON | L | н | L |
| Receiver One ON, Driver Zero OFF, Driver One ON L Receiver Zero ON, Driver Zero ON, Driver One ON H Receiver One ON, Driver Zero ON, Driver One ON H Driver Zero and Driver One TRI-STATE L | F | river Zero ON, Driver One OFF | Н | L | Н |
| Receiver Zero ON, Driver Zero ON, Driver One ON H Receiver One ON, Driver Zero ON, Driver One ON H Driver Zero and Driver One TRI-STATE L | N | river Zero OFF, Driver One ON | L | н | Н |
| Receiver One ON, Driver Zero ON, Driver One ON H Driver Zero and Driver One TRI-STATE L | ٧ | Driver Zero ON, Driver One ON | Н | н | L |
| Driver Zero and Driver One TRI-STATE | 1 | river Zero ON, Driver One ON | Н | Н | Н |
| | | er One TRI-STATE | L | L | Х |

Truth Table for Receiver Zero

| INPUTS | | | Ουτι | PUTS |
|--------|------------------------|----------------------|------|------|
| DE0 | DE0 RSEL (RI0+)-(RI0-) | | | DO- |
| Н | L | L | L | Н |
| Н | L | Н | Н | L |
| Н | L | 100 mV > & > -100 mV | Х | Х |
| L | Х | Х | Z | Z |

Truth Table for Receiver One INPUTS OUTPUTS

| DE1 | RSEL | (RI1+)–(RI1–) | DO+ | DO- |
|-----|------|----------------------|-----|-----|
| Н | н | L | L | Н |
| Н | н | Н | Н | L |
| Н | н | 100 mV > & > -100 mV | Х | Х |
| L | Х | Х | Z | Z |

X = High or low logic state Z = High impedance state

L = Low state

| Truth Table for | or Current | Drive |
|-----------------|------------|-------|
|-----------------|------------|-------|

X = High or low logic state Z = High impedance state

L = Low state

| Driver | Current Drive | ISEL0 | ISEL1 |
|----------|---------------|-------|-------|
| Driver 0 | 3.5 mA | Н | Х |
| Driver 0 | 8.5 mA | L | Х |
| Driver 1 | 3.5 mA | Х | н |
| Driver 1 | 8.5 mA | Х | L |

Applications Information

There are few common practices which should be employed when designing PCB for Bus LVDS signaling. Recommended practices are:

- Use at least 4 PCB board layer (Bus LVDS signals, ground, power and TTL signals).
- Keep drivers and receivers as close to the (Bus LVDS port side) connector as possible.
- Bypass each Bus LVDS device and also use distributed bulk capacitance. Surface mount capacitors placed close to power and ground pins work best. Two or three multilayer ceramic (MLC) surface mount capacitors (0.1µ and 0.01 μF in parallel should be used between each $V_{\rm CC}$ and ground. The capacitors should be as close as possible to the V_{CC} pin.
- Use controlled impedance traces which match the differential impedance of your transmission medium (i.e., Cable) and termination resistor.
- Use the termination resistor which best matches the differential impedance of your transmission line.
- Leave unused Bus LVDS receiver inputs open (floating).
- · Isolate TTL signals from Bus LVDS signals.

MEDIA (CABLE, CONNECTOR OR BACKPLANE) SELECTION:

Use controlled impedance media. The cables and connectors should have a matched differential impedance.

- Balanced cables (e.g., twisted pair) are usually better than unbalanced cables (ribbon cable, simple coax) for noise reduction and signal quality.
- There are different types of failsafe situations to consider, these are Open Input, Terminated Input, and other special cases. The first, Open input failsafe occurs when only one receiver is being used (R0 for example). The unused receiver (R1) inputs should be left open for noise minimization. The second case is for terminated inputs. This occurs when the inputs have a low impedance (typically 100 Ohm) termination (R $_{\rm T}$) across them, and the cable is unplugged. For this case, and if the output state needs to maintain a known state, two external bias resistors may be used to provide a strong common mode bias point. For this a 10K Ohm pull up and pull down resistor may be used to set the output high. Note that R1 and R2 should be much larger (2 orders of magnitude) compared to R $_{\rm T}$ to minimize loading effects to the Bus LVDS driver when it is active.



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